

## Transform from $\Omega$ to Another Basis $C$

We know that alternate sets of color matching functions can exist that are linear transformations of one another. One may ask, given two such sets of functions, how to find the  $3 \times 3$  matrix that converts the one to the other? The discussion below applies if one of the sets of CMFs is the orthonormal basis.

Suppose that  $\Omega$  is the orthonormal basis, derived from the 2° observer. We recall then that  $\Omega$  comprises 3 column vectors,

$$\Omega = [|\omega_1\rangle \quad |\omega_2\rangle \quad |\omega_3\rangle] \quad . \quad (1)$$

Suppose further that  $A$  is a different basis, also derived from the 2° observer. It's not important that the specific standard observer is used, but in any case, we know that the one set of functions is a linear transformation of the other set, which can be written as

$$A = \Omega T \quad . \quad (2)$$

Since each basis is represented by the 3 columns of a matrix, the transformation is written as square matrix  $T$ , which then post-multiplies  $\Omega$  to give  $A$ .

The orthonormal property of  $\Omega$  can be written in matrix form:

$$\Omega^T \Omega = I_{3 \times 3} \quad . \quad (3)$$

Of course, superscript T indicates matrix transpose, nothing to do with square matrix  $T$ .

We now wish to solve Eq. (2) for  $T$ . Left-multiply Eq. (2) by  $\Omega^T$  to obtain

$$\Omega^T A = \Omega^T \Omega T \quad . \quad (4)$$

Note from Eq. (3) that  $\Omega^T \Omega$  is the identity matrix, so it can be omitted in Eq. (4) and we find

$$T = \Omega^T A \quad , \quad (5)$$

the result that was sought.

Eq. (5) has practical application in computer work. It can happen that  $\Omega$  and some  $A$  have been found from a starting point such as [x-bar y-bar z-bar] by some steps, but  $T$  is not known.

The derivation could jump from Eq. (2) to Eq. (5) with a few words of explanation, but here the assumptions and details have been explained.